# Scientific Computing <br> Maastricht Science Program 

## Week 6

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## The World is Dynamic

- Many problems studied in science are 'dynamic'
- change over time
- Examples:
- change of temperature
- trajectory of a baseball
- populations of animals
- changes of price in stocks or options


Visualization of heat transfer in a pump casing
Heat is generated internally, cooled at the boundary $\rightarrow$ steady state temperature distribution.

- Commonly modeled with differential equations
- (Not to be confused with difference equations)


## Recap Difference Equations

- Remember difference equations (week1, week5)
- e.g. polulation growth:

$$
\begin{aligned}
P_{t} & =P_{t-1}+\Delta P_{t-1} \\
\Delta P_{t-1} & =(b-d) P_{t-1}
\end{aligned}
$$

- discrete time steps
- Now differential equations: continuous time


## Differential Equations

- Simple growth of bacteria model:

$$
r(t)=C p(t)
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- r - rate of growth
- p-population size


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Question to solve:

- How many bacteria are there at some time $t$
- given $p\left(t_{0}\right)=41$ ?
- More general: find $p(t)$ for some range $a<t<b$


## Differential Equations

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Contrast this with $\Delta P_{t-1}$ in difference equations
$\rightarrow$ now the change also needs to be a continuous function of time!

## Differential Equations

- Simple growth of bacteria model:

$$
\frac{d p(t)}{d t}=C p(t) \longrightarrow p^{\prime}(t)=C p(t)
$$

- r - rate of growth
- p-population size

Also:

$$
\begin{aligned}
& \dot{p}(t)=C p(t) \\
& \dot{p}=C p
\end{aligned}
$$

## Differential Equations

- Simple growth of bacteria model:

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\frac{d p(t)}{d t}=C p(t) \longrightarrow p^{\prime}(t)=C p(t)
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- r - rate of growth
- $p$ - population size
- Different types
- ordinary (ODEs) : all derivatives w.r.t. 1 'independent variable' (vs. 'partial DE' with multiple variables)
- Order of a DE: maximum order of differentiation.


## Problem

- Given an ODE

$$
y^{\prime}(t)=f(t, y(t)), \quad \forall t \in I
$$

- some time interval
- find a function $y(t)$ that satisfies it.


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- Given an ODE

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- find a function $y(t)$ that satisfies it.
- But: there are infinitely many solutions!



## Direction Fields

$$
f(t, y(t))=C y(t)
$$

- Given an ODE

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- Many functions satisfy it...
- Let's plot the derivatives...



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## Initial Value problem

- Given an ODE

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$$

- find a function $y(t)$ that satisfies it.
- Initial Value Problem (also: 'Cauchy Problem')
- specifies $y\left(t_{d}\right)$
$\rightarrow$ unique solution



## Initial Value problem

- Initial value problem:

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& y^{\prime}(t)=f(t, y(t)), \quad \forall t \in I \\
& y\left(t_{0}\right)=y_{0}
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- find a function $y(t)$ that satisfies it



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- find a function $y(t)$ that satisfies it However...
- closed-form solutions $y(t)$ only available for very special cases.
$\rightarrow$ Need for numerical solutions!
Approach
- Discretization: divide interval / in short steps of length $h$
- At each node $t_{n}$ compute $u_{n} \approx y\left(t_{n}\right)$
- Numerical solution: $\left\{u_{0}, u_{1}, \ldots, u_{N}\right\}$


## Initial Value problem

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- find a function $v(t)$ that satisfies However...
- closed-form solutions $y(t)$ only available for Effectively we
$\rightarrow$ Need for numerical solutions!
Approach
perform a simulation!
- Discretization: divide interval / in short s
- At each node $t_{n}$ compute $u_{n} \approx y\left(t_{n}\right)$
- Numerical solution: $\left\{u_{0}, u_{1}, \ldots, u_{N}\right\}$


## Forward Euler Method

- The forward Euler method
- just perform the 'simulation'
- shorthand $f_{n}=f\left(t_{n}, u_{n}\right)$

$$
u_{n+1}=u_{n}+h f_{n}
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Example

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u_{0}=12740
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$t=(0,19)$
$h=1$
$p(0)=12740$
$r(p)=0.1$ * $p$

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Example

$$
\begin{aligned}
& u_{0}=12740 \\
& u_{1}=u_{0}+h * r\left(u_{0}\right)=12740+1 * 1274.0=14014
\end{aligned}
$$

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Example

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t=(0,19)
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$$
\mathrm{h}=1
$$

$$
p(0)=12740
$$

$$
r(p)=0.1 * p
$$

$$
\begin{aligned}
& u_{0}=12740 \\
& u_{1}=u_{0}+h * r\left(u_{0}\right)=12740+1 * 1274.0=14014 \\
& u_{2}=u_{1}+h * r\left(u_{1}\right)=14014+1 * 1401.4=15415.40
\end{aligned}
$$

## Forward Euler Method - Errors

- Errors...



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## Computational Issues

- How accurate is this?
- Does it 'converge' ?
- What is the order $p$ of convergence?


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Can we deriver an expression for the error?
if $h \rightarrow 0$,
" Does it 'converge' ? does error $\rightarrow 0$ ?

- What is the order $p$ of convergence?

Do we have

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|e r r|<C(h)=O\left(h^{p}\right)
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## Computational Issues

- How accurate is this?

Can we deriver an expression for the error?
if $h \rightarrow 0$,
" Does it 'converge' ?

$$
\text { does error } \rightarrow 0 \text { ? }
$$

- What is the order $p$ of convergence?
- forward Euler method converges with order 1
- roughly: "h twice as small $\rightarrow$ error twice as small"
- the book discusses many methods with higher order.

Do we have
$|e r r|<C(h)=O\left(h^{p}\right)$

- Matlab implements many:
ode23, ode45, ode113, ode15s, ode23s, ode23t, ode23tb
- "doc ode23"


## Computational Issues

- Do they matter?
" yes...
- what to use? Matlab's doc:
"ode45 should be first you try"


